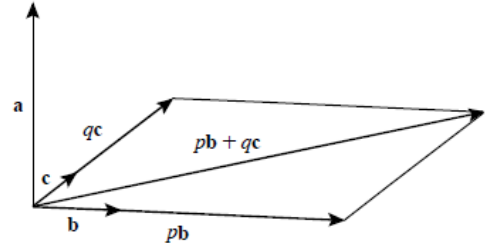


11.3

60. \mathbf{a} is orthogonal to $\mathbf{b} \Rightarrow \mathbf{a} \cdot \mathbf{b} = 0$ and \mathbf{a} is orthogonal to $\mathbf{c} \Rightarrow \mathbf{a} \cdot \mathbf{c} = 0$.
 Thus, $\mathbf{a} \cdot (p\mathbf{b} + q\mathbf{c}) = \mathbf{a} \cdot (p\mathbf{b}) + \mathbf{a} \cdot (q\mathbf{c}) = p(\mathbf{a} \cdot \mathbf{b}) + q(\mathbf{a} \cdot \mathbf{c}) = 0$,
 showing that \mathbf{a} is orthogonal to $p\mathbf{b} + q\mathbf{c}$. To interpret the result
 geometrically, observe that the vector $p\mathbf{b} + q\mathbf{c}$ lies in the plane determined
 by \mathbf{b} and \mathbf{c} . Since \mathbf{a} is orthogonal to both \mathbf{b} and \mathbf{c} , it is orthogonal to any
 vector lying in the plane determined by \mathbf{b} and \mathbf{c} .

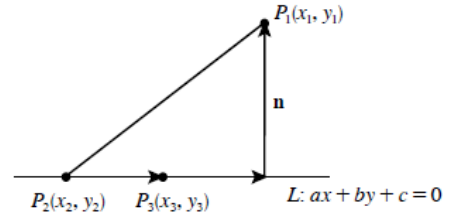


63. a. Pick $P_3(x_3, y_3)$ to be a point on L distinct from $P_2(x_2, y_2)$ and consider

$$\begin{aligned} \mathbf{n} \cdot \overrightarrow{P_2P_3} &= \langle a, b \rangle \cdot \langle x_3 - x_2, y_3 - y_2 \rangle = a(x_3 - x_2) + b(y_3 - y_2) \\ &= (ax_3 + by_3) - (ax_2 + by_2) \quad (1) \end{aligned}$$

Since P_2 and P_3 both lie on L , we have $ax_2 + by_2 = -c$ and

$ax_3 + by_3 = -c$. Substituting into (1) gives $\mathbf{n} \cdot \overrightarrow{P_2P_3} = -c - (-c) = 0$,
 so \mathbf{n} is orthogonal to L .



b. $d = \frac{|\overrightarrow{P_1P_2} \cdot \mathbf{n}|}{|\mathbf{n}|} = \frac{|(x_2 - x_1, y_2 - y_1) \cdot \langle a, b \rangle|}{\sqrt{a^2 + b^2}} = \frac{|a(x_2 - x_1) + b(y_2 - y_1)|}{\sqrt{a^2 + b^2}}$. Since $P_2(x_2, y_2)$ lies on L ,

$$ax_2 + by_2 = -c, \text{ so } d = \frac{|ax_1 + by_1 + c|}{\sqrt{a^2 + b^2}}.$$

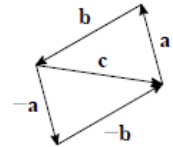
c. Here $P_1(1, -3)$ and $L : 2x + 3y - 6 = 0$, so $d = \frac{|2(1) + 3(-3) - 6|}{\sqrt{4 + 9}} = \frac{13}{\sqrt{13}} = \sqrt{13}$.

11.4

$$\begin{aligned}
 43. \quad \mathbf{a} \times (\mathbf{b} \times \mathbf{c}) + \mathbf{b} \times (\mathbf{c} \times \mathbf{a}) + \mathbf{c} \times (\mathbf{a} \times \mathbf{b}) &= (\mathbf{a} \cdot \mathbf{c}) \mathbf{b} - (\mathbf{a} \cdot \mathbf{b}) \mathbf{c} + (\mathbf{b} \cdot \mathbf{a}) \mathbf{c} - (\mathbf{b} \cdot \mathbf{c}) \mathbf{a} + (\mathbf{c} \cdot \mathbf{b}) \mathbf{a} - (\mathbf{c} \cdot \mathbf{a}) \mathbf{b} \\
 &= (\mathbf{a} \cdot \mathbf{c}) \mathbf{b} - (\mathbf{a} \cdot \mathbf{b}) \mathbf{c} + (\mathbf{a} \cdot \mathbf{b}) \mathbf{c} - (\mathbf{b} \cdot \mathbf{c}) \mathbf{a} + (\mathbf{b} \cdot \mathbf{c}) \mathbf{a} - (\mathbf{a} \cdot \mathbf{c}) \mathbf{b} = \mathbf{0}
 \end{aligned}$$

$$\begin{aligned}
 44. \quad (\mathbf{a} \times \mathbf{b}) \cdot (\mathbf{c} \times \mathbf{d}) &= [(\mathbf{a} \times \mathbf{b}) \times \mathbf{c}] \cdot \mathbf{d} = [-\mathbf{c} \times (\mathbf{a} \times \mathbf{b})] \cdot \mathbf{d} = -[(\mathbf{c} \cdot \mathbf{b}) \mathbf{a} - (\mathbf{c} \cdot \mathbf{a}) \mathbf{b}] \cdot \mathbf{d} \\
 &= (\mathbf{c} \cdot \mathbf{a}) (\mathbf{b} \cdot \mathbf{d}) - (\mathbf{c} \cdot \mathbf{b}) (\mathbf{a} \cdot \mathbf{d}) = (\mathbf{a} \cdot \mathbf{c}) (\mathbf{b} \cdot \mathbf{d}) - (\mathbf{b} \cdot \mathbf{c}) (\mathbf{a} \cdot \mathbf{d}) = \begin{vmatrix} \mathbf{a} \cdot \mathbf{c} & \mathbf{b} \cdot \mathbf{c} \\ \mathbf{a} \cdot \mathbf{d} & \mathbf{b} \cdot \mathbf{d} \end{vmatrix}
 \end{aligned}$$

46. a. By the parallelogram law of vector addition, we have $-\mathbf{a} + (-\mathbf{b}) = \mathbf{c} \Leftrightarrow \mathbf{a} + \mathbf{b} + \mathbf{c} = \mathbf{0}$ as in the figure.



b. $\mathbf{a} \times (\mathbf{a} + \mathbf{b} + \mathbf{c}) = \mathbf{a} \times \mathbf{0} \Rightarrow \mathbf{a} \times \mathbf{b} + \mathbf{a} \times \mathbf{c} = \mathbf{0}$ because $\mathbf{a} \times \mathbf{a} = \mathbf{0}$, and $\mathbf{c} \times (\mathbf{a} + \mathbf{b} + \mathbf{c}) = \mathbf{c} \times \mathbf{0} \Rightarrow \mathbf{c} \times \mathbf{a} + \mathbf{c} \times \mathbf{b} = \mathbf{0} \Rightarrow -\mathbf{a} \times \mathbf{c} - \mathbf{b} \times \mathbf{c} = \mathbf{0}$. Thus, $\mathbf{a} \times \mathbf{b} - \mathbf{b} \times \mathbf{c} = \mathbf{0} \Rightarrow \mathbf{a} \times \mathbf{b} = \mathbf{b} \times \mathbf{c}$. Next, $\mathbf{b} \times (\mathbf{a} + \mathbf{b} + \mathbf{c}) = \mathbf{0} \Rightarrow \mathbf{b} \times \mathbf{a} + \mathbf{b} \times \mathbf{c} = \mathbf{0}$, so $\mathbf{b} \times \mathbf{c} = \mathbf{c} \times \mathbf{a}$. Thus, $\mathbf{a} \times \mathbf{b} = \mathbf{b} \times \mathbf{c} = \mathbf{c} \times \mathbf{a} \Rightarrow |\mathbf{a} \times \mathbf{b}| = |\mathbf{b} \times \mathbf{c}| = |\mathbf{c} \times \mathbf{a}| \Rightarrow |\mathbf{a}| |\mathbf{b}| \sin C = |\mathbf{b}| |\mathbf{c}| \sin A = |\mathbf{c}| |\mathbf{a}| \sin B$, and dividing by $|\mathbf{a}| |\mathbf{b}| |\mathbf{c}|$ yields $\frac{\sin C}{c} = \frac{\sin A}{a} = \frac{\sin B}{b}$, where $a = |\mathbf{a}|$, $b = |\mathbf{b}|$, and $c = |\mathbf{c}|$.

52. Let $\mathbf{a} = a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k}$, $\mathbf{b} = b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k}$, and $\mathbf{c} = c_1\mathbf{i} + c_2\mathbf{j} + c_3\mathbf{k}$. Then

$$\mathbf{b} \times \mathbf{c} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = (b_2c_3 - b_3c_2)\mathbf{i} - (b_1c_3 - b_3c_1)\mathbf{j} + (b_1c_2 - b_2c_1)\mathbf{k} \text{ and}$$

$$\begin{aligned}
 \mathbf{a} \times (\mathbf{b} \times \mathbf{c}) &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a_1 & a_2 & a_3 \\ b_2c_3 - b_3c_2 & b_3c_1 - b_1c_3 & b_1c_2 - b_2c_1 \end{vmatrix} \\
 &= [a_2(b_1c_2 - b_2c_1) - a_3(b_3c_1 - b_1c_3)]\mathbf{i} - [a_1(b_1c_2 - b_2c_1) - a_3(b_2c_3 - b_3c_2)]\mathbf{j} \\
 &\quad + [a_1(b_3c_1 - b_1c_3) - a_2(b_2c_3 - b_3c_2)]\mathbf{k}
 \end{aligned}$$

On the other hand,

$$\begin{aligned}
 (\mathbf{a} \cdot \mathbf{c}) \mathbf{b} - (\mathbf{a} \cdot \mathbf{b}) \mathbf{c} &= (a_1c_1 + a_2c_2 + a_3c_3)(b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k}) - (a_1b_1 + a_2b_2 + a_3b_3)(c_1\mathbf{i} + c_2\mathbf{j} + c_3\mathbf{k}) \\
 &= (a_1b_1c_1 + a_2b_1c_2 + a_3b_1c_3 - a_1b_1c_1 - a_2b_2c_1 - a_3b_3c_1)\mathbf{i} \\
 &\quad + (a_1b_2c_1 + a_2b_2c_2 + a_3b_2c_3 - a_1b_1c_2 - a_2b_2c_2 - a_3b_3c_2)\mathbf{j} \\
 &\quad + (a_1b_3c_1 + a_2b_3c_2 + a_3b_3c_3 - a_1b_1c_3 - a_2b_2c_3 - a_3b_3c_3)\mathbf{k} \\
 &= (a_2b_1c_2 + a_3b_1c_3 - a_2b_2c_1 - a_3b_3c_1)\mathbf{i} \\
 &\quad - (a_1b_1c_2 + a_3b_3c_2 - a_1b_2c_1 - a_3b_2c_3)\mathbf{j} \\
 &\quad + (a_1b_3c_1 + a_2b_3c_2 - a_1b_1c_3 - a_2b_2c_3)\mathbf{k}
 \end{aligned}$$

The result follows when we compare the two expressions.

11.5

7. Let $A(2, 1, 4)$ and $B(1, 3, 7)$. Then $\mathbf{v} = \overrightarrow{AB} = \langle -1, 2, 3 \rangle$ is parallel to the required line. Thus, parametric equations of the line are $x = 2 - t, y = 1 + 2t, z = 4 + 3t$ and symmetric equations are $\frac{x-2}{-1} = \frac{y-1}{2} = \frac{z-4}{3}$.

32. Let $A(2, 3, -1), B(1, -2, 3)$, and $C(-1, 2, 4)$. Then $\overrightarrow{AB} = \langle -1, -5, 4 \rangle$ and $\overrightarrow{AC} = \langle -3, -1, 5 \rangle$. A normal to the

required plane is $\mathbf{n} = \overrightarrow{AB} \times \overrightarrow{AC} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -1 & -5 & 4 \\ -3 & -1 & 5 \end{vmatrix} = \langle -21, -7, -14 \rangle = -7\langle 3, 1, 2 \rangle$, so an equation of the plane is

$$3(x-2) + 1(y-3) + 2(z+1) = 0 \Leftrightarrow 3x + y + 2z = 7.$$

62. A vector parallel to the line passing through $(-1, 3, -1)$ and $(1, 2, 3)$ is $\mathbf{u} = \langle 2, -1, 4 \rangle$. Taking $P(1, 4, 2)$

and $Q(1, 2, 3)$ and using the result of Exercise 59, we find $\overrightarrow{QP} \times \mathbf{u} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 2 & -1 \\ 2 & -1 & 4 \end{vmatrix} = 7\mathbf{i} - 2\mathbf{j} - 4\mathbf{k}$, so

$$D = \frac{\overrightarrow{QP} \times \mathbf{u}}{|\mathbf{u}|} = \frac{|7\mathbf{i} - 2\mathbf{j} - 4\mathbf{k}|}{\sqrt{4+1+16}} = \frac{\sqrt{69}}{\sqrt{21}} = \frac{\sqrt{161}}{7}.$$

63. Let us denote the planes by $\pi_1 : ax + by + cz = d_1$ and $\pi_2 : ax + by + cz = d_2$. Choose a point $P(x_0, y_0, z_0)$ on π_1 and observe that a normal to π_2 is $\mathbf{n} = \langle a, b, c \rangle$. So, using the result of Exercise 59, $D = \frac{|ax_0 + by_0 + cz_0 - d_2|}{\sqrt{a^2 + b^2 + c^2}}$. But since

$P(x_0, y_0, z_0)$ lies on π_1 , it satisfies the equation of the plane; that is, $ax_0 + by_0 + cz_0 = d_1$. Thus, $D = \frac{|d_1 - d_2|}{\sqrt{a^2 + b^2 + c^2}}$.